

UNISONIC TECHNOLOGIES CO., LTD

UTRS3085S

Preliminary

CMOS IC

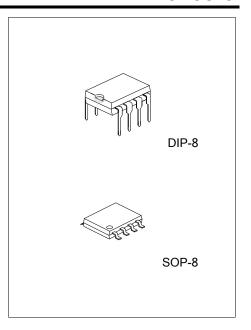
FAIL-SAFE, 1.0MBPS, RS-485 / RS-422 TRANSCEIVERS WITH +15KV ESD-PROTECTED

■ DESCRIPTION

The UTC **UTRS3085S** high-speed transceivers for RS-485/RS-422 communication contain one driver and one receiver. The device features fail-safe circuitry, which guarantees a logic-high receiver output when the receiver inputs are open or shorted. This means that the receiver output will be logic high if all transmitters on a terminated bus are disabled (high impedance). The UTC **UTRS3085S** offer higher driver output slew-rate limits, allowing transmission up to 1.0Mbps.

The transceiver typically draws 375µA of supply current when unloaded or when fully loaded with the drivers disabled.

A device has a 1/8-unit-load receiver input impedance that allows up to 256 transceivers on the bus.

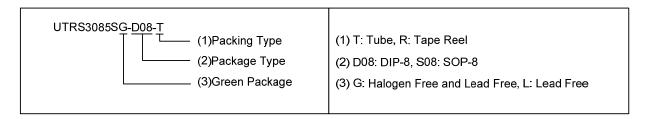


■ FEATURES

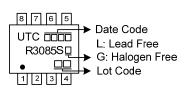
- * True fail-safe receiver while maintaining EIA/TIA-485 compatibility.
- * Enhanced slew-rate limiting facilitates Error-Free data transmission.
- * 5.0V single power supply.
- * 1µA low-current shutdown mode.
- * Allow up to 256 transceivers on the Bus.
- * HBM ±15kV ESD protection for Transmitter Output
- * Driver short circuit current limit.
- * Thermal shutdown for overload protection.

ORDERING INFORMATION

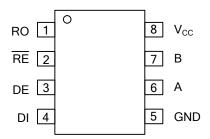
Ordering	Number	Doolsono	Dealine	
Lead Free Halogen Free		Package	Packing	
UTRS3085SL-D08-T	UTRS3085SG-D08-T	DIP-8	Tube	
UTRS3085SL-S08-R UTRS3085SG-S08-		SOP-8	Tape Reel	



MARKING



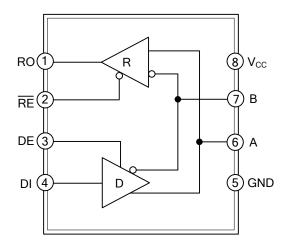
■ PIN CONFIGURATION



■ PIN DESCRIPTION

PIN NO.	PIN NAME	DESCRIPTION
1	RO	Receiver output.
2	RE	Receiver output enable. Drive \overline{RE} low to enable RO; RO is high impedance when \overline{RE} is high. Drive \overline{RE} high and DE low to enter low-power shutdown mode.
3	DE	Driver output enable. Drive DE high to enable driver outputs. These outputs are high impedance when DE is low. Drive $\overline{\text{RE}}$ high and DE low to enter low-power shutdown mode.
4	DI	Driver input. With DE high, a low on DI forces non-inverting output low and inverting output high. Similarly, a high on DI forces non-inverting output high and inverting output low.
5	GND	Ground
6	Α	Non-inverting receiver input and non-inverting driver output
7	В	Inverting receiver input and inverting driver output
8	Vcc	Positive supply, 4.75V≤V _{CC} ≤5.25V

■ BLOCK DIAGRAM



ABSOLUTE MAXIMUM RATING

PARAMETER		SYMBOL	RATINGS	UNIT
Supply Voltage		Vcc	+7.0	V
Control Input Voltage (RE, DE)			-0.3 ~ (V _{CC} +0.3)	V
Driver Input Voltage		DI	-0.3 ~ (V _{CC} +0.3)	V
Receiver Input Voltage (A, B)			±12.5	V
Receiver Output Voltage (RO)			-0.3 ~ (V _{CC} +0.3)	V
Continuous Power Dissipation DIP-8			550	mW
(Derate 5.88mW/°C above +70°C) SOP-8		P _D	471	mW
Operating Temperature Ranges		Topr	-40 ~ +85	°C
Storage Temperature Range		T _{STG}	-65 ~ + 150	°C

Note: Absolute maximum ratings are only stress ratings and it is not implied for functional device operation. Absolute maximum ratings are the values beyond which the device will be damaged permanently.

■ DC ELECTRICAL CHARACTERISTICS

 $(V_{CC}=+5.0V \pm 5\%, T_A=T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } V_{CC}=+5.0V \text{ and } T_A=+25^{\circ}C) \text{ (Note 1)}$

	1111 011,	outer wide herea. Typical values are a			,	()
PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
DRIVER						
Differential Driver Output (No Load)	V _{OD1}	Fig.1			5.0	V
Differential Driver Outroot	M	Fig.1, R=50Ω (RS-422)	1.8			V
Differential Driver Output	V _{OD2}	Fig.1, R=27Ω (RS-485)	1.4			V
Change in Magnitude of Differential Output Voltage (Note 2)	ΔVod	Fig.1, R=50Ω or R=27Ω			0.2	V
Driver Common-Mode Output Voltage	Voc	Fig.1, R=50Ω or R=27Ω			3.0	V
Change In Magnitude of Common-Mode Voltage (Note 2)	ΔVος	Fig.1, R=50Ω or R=27Ω			0.2	V
Input High Voltage	V _{IH1}	DE, DI, RE	2.0			V
Input Low Voltage	V _{IL1}	DE, DI, RE			8.0	V
DI Input Hysteresis	V _{HYS}			100		mV
Input Current	I _{IN1}	DE, DI, RE			±2.0	μΑ
Innut Current (A and D)	Long	DE=GND, V _{IN} =12V			125	μΑ
Input Current (A and B)	I _{IN2}	Vcc=GND or 5.25V V _{IN} =-7V			-75	μΑ
Driver Short-Circuit Output		-7V≤V _{OUT} ≤V _{CC}	-250			mA
Current (Note 4)	V _{OD1}	0V≤V _{OUT} ≤12V			250	mA
Current (Note 4)		0V≤V _{OUT} ≤V _{CC}	±25			mA
RECEIVER	T		1	,		ı
Receiver Differential Threshold Voltage	V _{TH}	V _{CM} =+2.5V	-200		-20	mV
Receiver Input Hysteresis	ΔV_{TH}			25		mV
Receiver Output High Voltage	Vон	Io=-4mA, V _{ID} =-20mV	Vcc-1.5			V
Receiver Output Low Voltage	Vol	Io=4mA, V _{ID} =-200mV			0.4	V
Three-State Output Current at Receiver	lozr	0.4V≤Vo≤2.4V			±1.0	μΑ
Receiver Input Resistance	Rin	-7V≤V _{CM} ≤+12V	96			kΩ
Receiver Output Short-Circuit Current	Iosr	0V≤V _{RO} ≤V _{CC}	±7		±95	mA

■ DC ELECTRICAL CHARACTERISTICS (Cont.)

PARAMETER	SYMBOL	TEST CONDITIONS		MIN	TYP	MAX	UNIT
SUPPLY CURRENT							
Committee Committee	Icc	No Load,	DE=V _{CC}		430	900	μΑ
Supply Current		RE =DI= V _{CC} or GND	DE=GND		375	600	μA
Supply Current in Shutdown Mode	Ishdn	DE=GND, V _{RE} =Vcc			1.0	10	μA

- Notes: 1. All currents into the device are positive; all currents out of the device are negative. All voltages are referred to device ground unless otherwise noted.
 - 2. ΔV_{OD} and ΔV_{OC} are the changes in V_{OD} and V_{OC} , respectively, when the DI input changes state.
 - 3. Maximum current level applies to peak current just prior to foldback-current limiting; minimum current level applies during current limiting.

SWITCHING CHARACTERISTICS

(V_{CC}=+5.0V ±5%, T_A=T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at V_{CC}=+5.0V and T_A=+25°C)

PARAMETER	SYMBOL	TEST CONDITIONS		TYP	MAX	UNIT
Driver Input to Output	t _{DPLH}	Fig 2 and 5 D		100		ns
Driver Input to Output	t _{DPHL}	Fig.3 and 5, R _{DIFF} =54Ω, C _{L1} =C _{L2} =100pF		100		ns
Driver Output Skew	t	Fig.3 and 5, R _{DIFF} =54Ω, C _{L1} =C _{L2} =100pF		5	200	ns
toplh - tophl	tdskew	Fig.3 and 5, RDIFF-5412, CL1-CL2-100PF				
Driver Rise or Fall Time	t _{DR} , t _{DF}	Fig.3 and 5, R _{DIFF} =54Ω, C _{L1} =C _{L2} =100pF		200		ns
Maximum Data Rate	f _{MAX}		1.0			Mbps
Driver Enable to Output High	t _{DZH}	Fig.4 and 6, C _L =100pF, S2 Closed			200	ns
Driver Enable to Output Low	t _{DZL}	Fig.4 and 6, C∟=100pF, S1 Closed			200	ns
Driver Disable Time from Low	t _{DLZ}	Fig.4 and 6, C∟=15pF, S1 Closed			200	ns
Driver Disable Time from High	t _{DHZ}	Fig.4 and 6, C∟=15pF, S2 Closed			200	ns
Receiver Input to Output	t _{RPLH} ,	Fig.7 and 9, V _{ID} ≥2.0V; Rise and Fall Time		200		ns
Receiver input to Output	t _{RPHL}	of V _{ID} ≤15ns		200		115
trplh - trphl Differential	trskd	Fig.7 and 9, V _{ID} ≥2.0V; Rise and Fall Time		50		ns
Receiver Skew	IRSKD	of V _{ID} ≤15ns		30		113
Receiver Enable to Output	t _{RZL}	Fig.2 and 8, C∟=100pF, S1 Closed		50		ns
Low	IRZL	1 lg.2 and 0, 01 100pi , 01 0103cd		30		110
Receiver Enable to Output	t _{RZH}	Fig.2 and 8, C∟=100pF, S2 Closed		50		ns
High	UNZIT	1 19.2 drid 0, 0E-100p1 , 02 01030d				113
Receiver Disable Time from	t _{RLZ}	Fig.2 and 8, C∟=100pF, S1 Closed		50		ns
Low	UNLZ	1 1g.2 and 6, 62 16661 , 61 616664				110
Receiver Disable Time from	t _{RHZ}	Fig.2 and 8, C∟=100pF, S2 Closed		50		ns
High	4412					1.0
Time to Shutdown	tshdn	Note 1		200		ns
Driver Enable from Shutdown	t _{DZH(SHDN)}	Fig.4 and 6, C∟=15pF, S2 Closed			4000	ns
to Output High	LDZH(SHDIN)	rig.+ and 0, 0t= ropr , 02 diosed			4000	110
Driver Enable from Shutdown	t _{DZL(SHDN)}	Fig.4 and 6, C∟=15pF, S1 Closed			4000	ns
to Output Low	IDZL(SHDIN)	i ig and o, ot lopi , or olosed			4000	113
Receiver Enable from	t _{RZH(SHDN)}	Fig.2 and 8, C∟=100pF, S2 Closed			3000	ns
Shutdown to Output High	uvzu(sudin)	rig.z aliu o, GL-100pr, 32 Glosed			3000	113
Receiver Enable from	trzl(SHDN)	Fig.2 and 8, C _L =100pF, S1 Closed			3000	ns
Shutdown to Output Low	(5.15/4)	J -, -2				

Note: The device is put into shutdown by bringing \overline{RE} high and DE low. If the enable inputs are in this state for less than 50ns, the device is guaranteed not to enter shutdown. If the enable inputs are in this state for at least 600ns, the device is guaranteed to have entered shutdown.

■ FUNCTION TABLE

TRANSMITTING

INPUTS			OUTPUTS		
RE	DE	DI	В	Α	
Х	1	1	0	1	
Х	1	0	1	0	
0	0	X	High-Z	High-Z	
1	0	X	Shutdown		

RECEIVING

INPUTS			OUTPUT
RE	DE	A-B	RO
0	X	≥-0.02V	1
0	X	≤-0.2V	0
0	X	Open/Shorted	1
1	1	X	High-Z
1	0	X	Shutdown

X = Don't care

Shutdown mode, driver and receiver outputs high impedance

■ TEST CIRCUIT

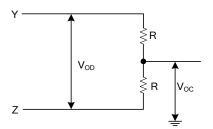


Fig. 1 Driver DC Test Circuit

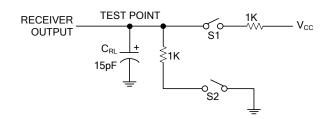


Fig. 2 Receiver Enable/Disable Timing Test Load

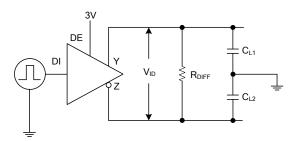


Fig. 3 Driver Timing Test Circuit

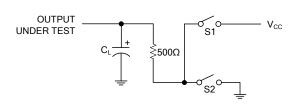


Fig. 4 Driver Enable/Disable Timing Test Load

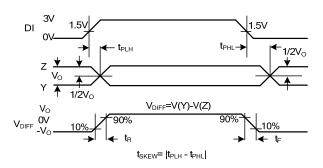


Fig. 5 Driver Propagation Delays

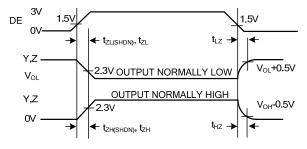


Fig. 6 Driver Enable and Disable Times

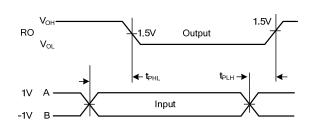


Fig. 7 Receiver Propagation Delays

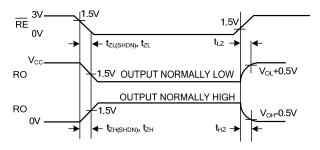


Fig. 8 Receiver Enable and Disable Times

TEST CIRCUIT (Cont.)

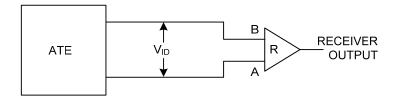
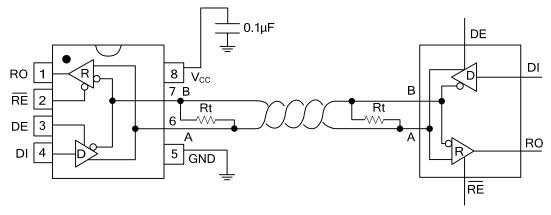


Fig. 9 Receiver Propagation Delay Test Circuit

TYPICAL APPLICATION CIRCUIT



Note: Pin labels Y and Z on timing, test, and waveform diagrams refer to pins A and B when DE is high.

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